

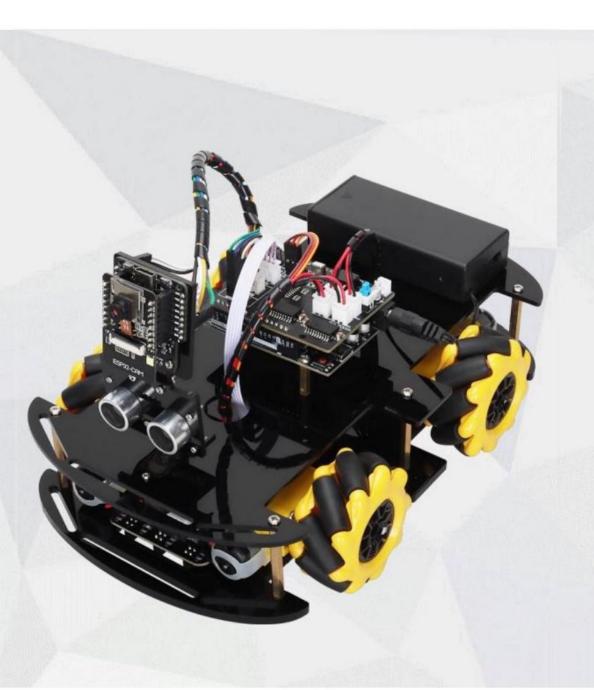
# SP32 CAM Mecanum Wheel Kit ZYC0076











Product performance parameters:

Working voltage:5v

Input voltage:7-12V

Maximum output current:2A

Maximum power consumption:25W(T=75℃)

Motor speed:5v 20Orpm/min

Ultrasonic sensing angle:<15 degrees

Ultrasonic detection distance:2cm~400cm

Bluetooth remote.control distance:10~50 meters

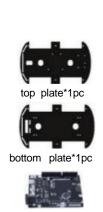
Servo motor angle range:0~180°10~360°

### Features:

- 1.Multifunctional:Mecanum wheel multi-directional movement,three-way tracking,ultrasonic obstacle avoidance and following,camera image transmission function,WIFI control function;
- 2. The assembly dificulty is moderate: no need to weld the circuit, the terminal connector is easy to insert, and the assembly manual is

provided to complete the assembly clearly and efficiently;

- 3. High strength: solid material bracket, thickened bottom plate, high-quality Mecanum wheels;
- 4. High extension: rich interfaces to expand other sensors and modules;
- 5.Basic programming:Arduino code based on C language;
- 6. Novel function: Combine Esp32 cam and arduino to realize multi-function wifi control.



Main control board\*1pc



Expansion board#1pc



Motor with 2P terminal wire\*4pcs module development board,



The McKnum Wheel (With coupling)\*4pcs



type-c line\*1pc

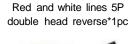






ESP32 CAM expansion board\*1pc

Phillips screwdriver1pc



line 4P20CM\*1pc



4P with terminal Dupont wire\*1pc

M3\*30 round head screw\*8pcs

M3\*16 round head screw\*2pcs

M3\*10 flat head screw4pcs



M3 Nut\*22pcs

M2 Nut\*6pcs

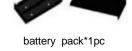
M1.6 Nut\*4pcs







Tracking module\*1pc





Ultrasonic bracket\*1pc



Ultrasonic module\*1pc

M2.5\*20 round head screw\*4pcs M3\*40 Copper column\*6pcs

M2\*10 round head screw\*6pcs

M1.6\*8 round head screw4pcs

M3\*8 round head screw\*28pcs

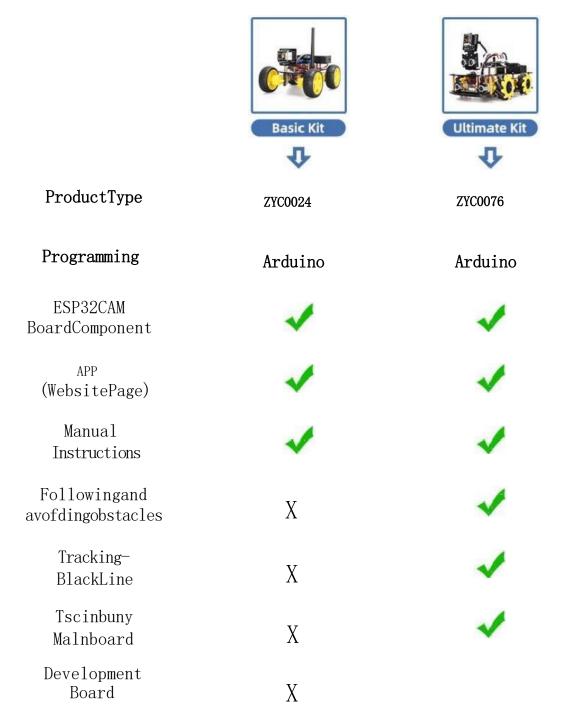


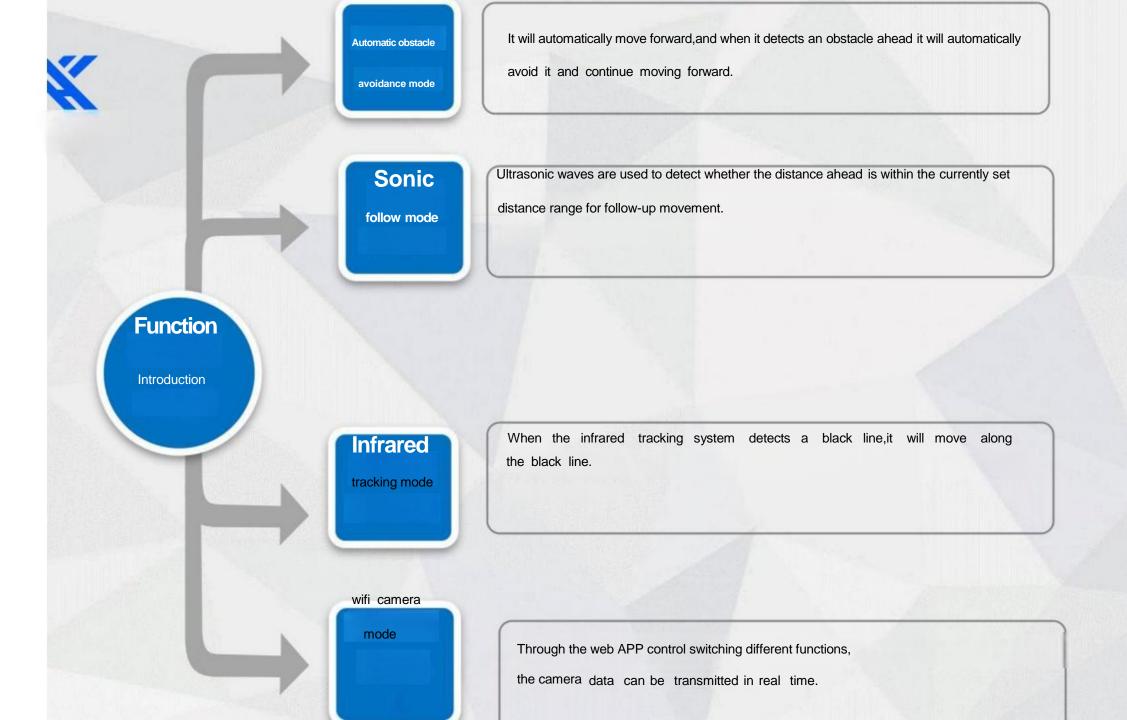
Motor frame\*4pcs ESP32-CAM bracket\*1pc





Product Weight: 970g







### **Target customer group**

### **Maker(Programming organization)**

The purpose of purchase is to use our products to realize some of his own DIY ideas







### student

By purchasing our products.you can learnArdulno programming knowledge

And parlcpate invarious elactonic DIY programming compettions.



## **Usage scenarios**

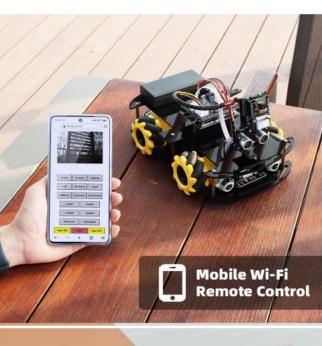




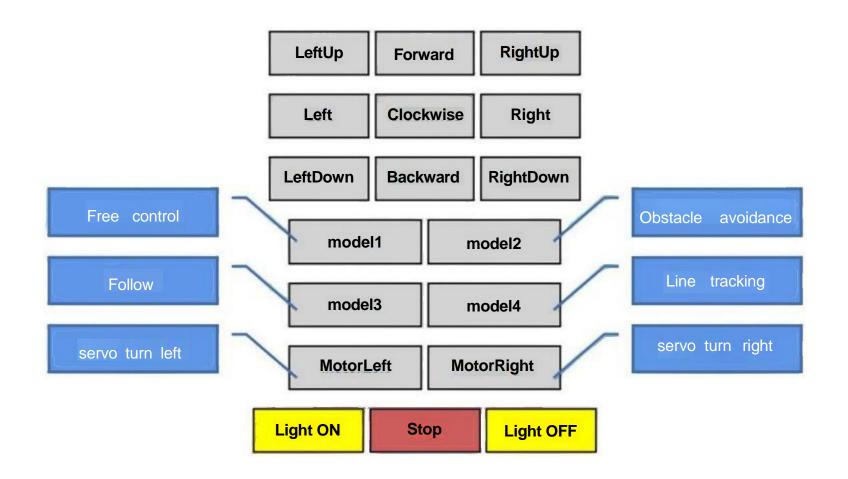


### **Function display scene**



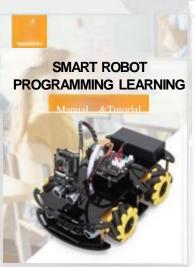


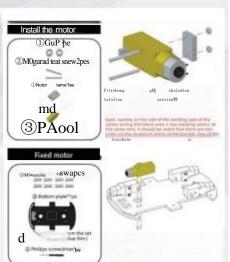


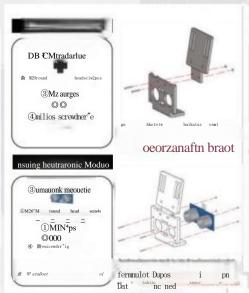


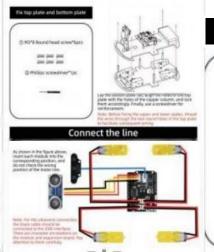


### **Tutorial part display**







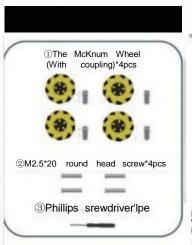


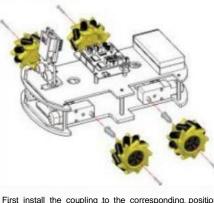
**③四**Ma2

 $\overline{\mathbf{x}}$ 

-5-

4s





First install the coupling to the corresponding position of the motor, and then align the wheel with intrastal it lock the screw, and finally reinforce with a screwdriver.

Note:Do not insert the Bluetooth module backwards.

0\_Assembl y\_Robot



1\_Arduino software



2\_Library S



3\_Tutorial document



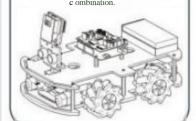
4\_Arduino \_Code



5\_datashe et

### The installation is complete

Here,congratulations you have completed the whole assembly of the car,then you can combine the code to explore the fun of the smart car,enjoy the joy of programming and toy c ombination.









The ESP32CAM camera main control board and the TSCINBUNY UNO control board are combined with the functionally

integrated Mecanum wheel multi-function expansion board to produce an inteligent vehicle control system with enhanced product

performance and stability.

- Provides a complete tutorial manual and related source code,based on Arduino development,with rich learning resources;
- DIY assembly and construction can cultivate children's hands-on ability.
- Product has diversified functions and high playability.



Thanks For Your Attention

