



Figure 1. Physical photo of ATLS2A202D

### FEATURES

- High Efficiency:  $\geq 90\%$
- Constant Current Output
- Maximum Output Current: 2A
- Current Output Noise:  $3.71\mu A_{P-P}$  @ 0.1Hz-10Hz
- High Stability: 100ppm/ $^{\circ}C$
- PWM Switching Frequency Synchronizable
- Zero EMI
- Compact Size
- DIP Package Available
- 100 % Lead (Pb)-free and RoHS Compliant
- SMT Package Available

### APPLICATIONS

Driving laser diodes with low noise, including DPSSL, EDFA, fiber laser, direct diode lasers, etc.

### DESCRIPTION

This laser driver is an electronic module designed for driving diode lasers with up to 2A constant current, high efficiency, low noise, high reliability, zero EMI, and small package. Figure 1 shows physical photo of ATLS2A202D.

Table 1. Pin Function Descriptions

Pin #	Name	Type	Description
1	SDN	Digital Input	Shut down control. Negative logic, at the internal chip control input: $>1.4V$ = enable, $<0.95V$ = shut down, normal threshold voltage = 1.2V.
2	SYNC	Synchronization Input	The default internal switching frequency is 500kHz. This pin can be connected to an external clock signal of which the frequency can be about 10% to 15% higher than the switching frequency. In this way, the driver will be switching at the same frequency with the external clock signal,

It provides these the functions: laser constant current control, laser current monitoring, over current and thermal protection, laser current output indication, laser diode status indication, soft start, and shut down.

It comes with a high stability low noise 2.5V voltage reference output which can be used for setting the output current. The reference output can also be used for the ADCs (Analog to Digital Converters) and/or DACs (Digital to Analog Converters).

The frequency synchronization of this laser driver allows using an external digital signal to synchronize the internal PWM output stage of the laser driver, to eliminate frequency beating interferences between the laser drivers and other switch mode electronic circuits on the same PCB.

The external signal needs to be in the range of 520kHz to 800kHz.

If other frequency is needed, contact us, we may be able to adjust the internal PWM frequency for you. The default switching frequency of the internal PWM output stage is 500kHz.

**Warning:** The through hole types of modules can only be soldered manually on the board by a solder iron of  $< 310^{\circ}C$  ( $590^{\circ}F$ ), not go through a reflow oven process.

The ATLS2A202D is packaged in a 6 sided metal enclosure, which blocks EMIs (Electro-Magnetic Interferences) to prevent the driver and other electronics from interfering each other.

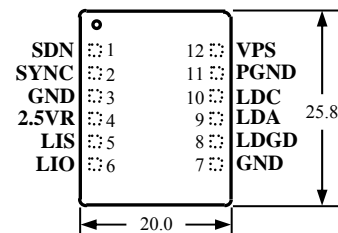


Figure 2. Pin Names and Locations

Figure 2 is the actual size top view of the ATLS2A202D, which shows the pin names and locations. Its thickness is 5.0mm.

The ATLS2A202D pin functions are shown in Table 1.

			eliminating beating interferences. If other switching frequency is needed, please tell us, it can be specified from 300kHz to 700kHz.
3, 7	GND	Signal Ground	Signal ground pin. Connect ADCs and DACs grounds to here.
4	2.5VR	Analog Output	Reference voltage. It can source 3mA max, with 5 $\mu$ V <sub>P-P</sub> noise @ 0.1 to 10Hz and 25ppm/ $^{\circ}$ C stability max.
5	LIS	Analog Input	Laser current set-point voltage. There is an input resistor of 10M tied to GND. Setting it from 0V to 2.5V will set the laser current from 0A to 2A linearly.
6	LIO	Analog Output	Laser current output indication. 0V to 2.5V indicates the laser current of from 0A to 2A linearly.
8	LDGD	Digital Output	Laser diode good. When this pin is high, >2V, the control loop is working properly. When this pin is low, <0.3V, the laser diode is bad, or there is a short or open circuit at the laser diode.
9	LDA	Analog Output	Laser diode anode. Connect it to the anode of the laser diode.
10	LDC	Analog Output	Laser diode anode. Connect it to the cathode of the laser diode.
11	PGND	Power Ground	Power ground pin. Connect this pin directly to power supply return pass.
12	VPS	Power Input	Power supply voltage. The driver will work from V <sub>VPS</sub> = 3.0V to 5.5V.

### SPECIFICATIONS

Table 2. Characteristics (T<sub>ambient</sub> = 25 $^{\circ}$ C)

Parameter	Value	Unit
Laser driver efficiency	$\geq 90$	%
Maximum output current	2	A
Current output noise (V <sub>IN</sub> = 5V; V <sub>OUT</sub> = 2.5V; I <sub>OUT</sub> = 500mA)	3.71	$\mu$ A <sub>P-P</sub> @ 0.1Hz- 10Hz
Stability	100	ppm/ $^{\circ}$ C
Laser current control signal level	0 ~ 2.5	V
Control accuracy	$\pm 0.2$	%
Laser current indication signal level	0 ~ 2.5	V
Indication accuracy	$\pm 0.2$	%
Output reference voltage	2.5	V
Power supply voltage range	3.0 ~ 5.5	V
Operating case temperature	-40 ~ 125	$^{\circ}$ C
Rise times of small signal	70	$\mu$ S
Fall times of small signal	70	$\mu$ S
Rise times of large signal	352	$\mu$ S
Fall times of large signal	184	$\mu$ S

### OPERATION PRINCIPLE

The block diagram of the driver is shown in Figure 3. The shut down control circuit accepts signals from 3 sources: external shut down, over current and over temperature signals. When one of these signals is activated, the driver is shut down. Only when all these 3 signals go up, the soft start circuit starts enabling the low noise driver.

It comes with a laser diode status indication circuit. When LDGD pin is high, >2V, the control loop is working properly. When this pin is low, <0.3V, the laser diode is bad, or there is a short or open circuit at the laser diode.

The high stability low noise 2.5V voltage reference can be used for setting the output current, and also be used for the ADCs and/or DACs.

An internal soft start circuit allows a slow start up and a quick shut down.

The current measurement circuit monitors the output current and shuts down the driver upon detecting the output current exceeds the pre-set value.

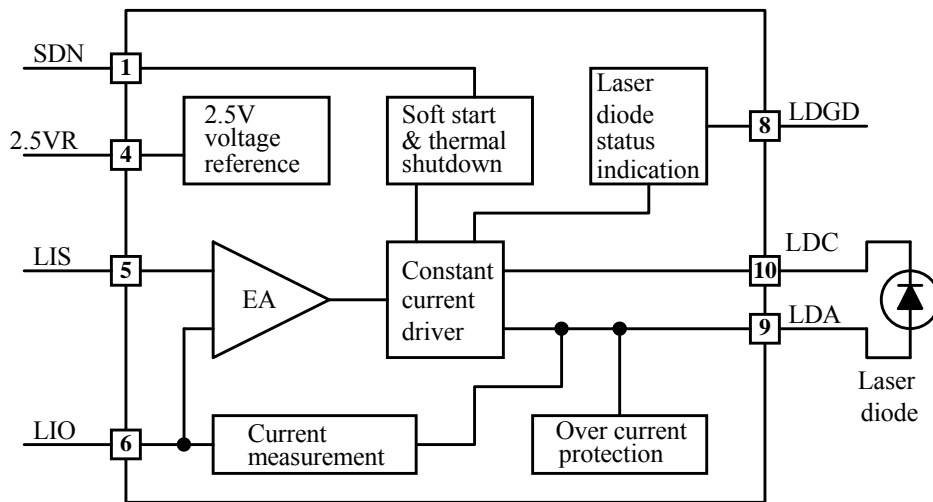


Figure 3. Block Diagram

### APPLICATIONS

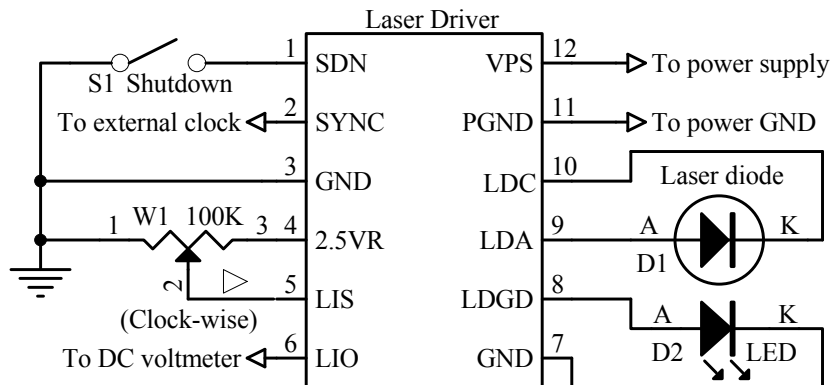


Figure 4. A Typical Stand-alone Application Schematic

Figure 4 shows a typical stand-alone application circuit.

In Figure 4, the switch S1 is external shut down switch, it can turn on and off the driver with the SDN pin high and lower respectively, at the internal chip control input:  $>1.4V$  = enable,  $<0.95V$  = shut down, normal threshold voltage =  $1.2V$ . The switch S1 can also be an electronic switch, such as an I/O pin of a micro-controller, with an either open drain or push/pull output. See Figure 5. If not using a switch (S1) to control the laser, leave the SDN pin unconnected.

If the SYNC isn't connected, the default internal switching frequency is 500kHz. This pin can also be connected to an external clock signal of which the frequency can be about 10% to 15% higher than the switching frequency. In this way, the driver will be switching at the same frequency with the external clock signal, eliminating beating interferences. If other switching frequency is needed, please tell us, it can be specified from 300kHz to 700kHz.

In Figure 4, the adjustable resistor W1 is used to setting the output current. Setting LIS from 0V to 2.5V will set the laser current from 0A to 2A linearly.

The laser diode D1 is connected between LDA and LDC. It is worth mentioning that the power supply return terminal should be connected to the pin 11 PGND and the cathode of the laser diode should be connected to the pin 10 LDC. These 2 nodes should not be connected together externally and they are connected together internally already by the driver.

In Figure 4, the LED D2 is used to indicating laser diode status. When LDGD pin is high,  $>2V$ , the laser diode control loop is working properly. When LDGD pin is low,  $<0.3V$ , the laser diode is bad, or there is a short or open circuit at the laser diode. The LDGD pin can also be connected to a digital input pin of a micro-controller, when software/firmware is utilized in the system. See Figure 5. Figure 5 shows a typical micro-processor-based application circuit.

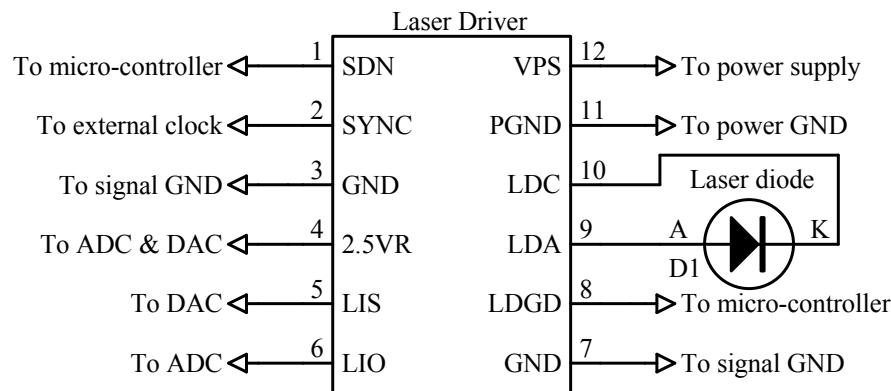


Figure 5. A Typical Micro-processor-based Application

### Turning the Driver On and Off

The driver can be turned on and off by setting the SDN pin high and lower respectively. It is recommended to turn the driver on by this sequence:

To turn on: turn on the power by providing the power supply voltage to the driver, turn on the driver by releasing the SDN pin.

To turn off: turn off the driver by lowering the voltage of SDN pin, turn off the power by stopping the voltage supply on the VPS pin.

When not controlling by the SDN pin: leave it unconnected and turn on and off the driver by the power supply.

### Adjusting the Output Current

The output current is set by adjusting W1, which sets input voltages of LIS, pin 5. See Figure 4. The output current will be:

$$I_{OUT} = 2.0 \times V_{LIS} / 2.5 \text{ (A)}.$$

LIS can be configured by using a DAC, to replace the W1 in Figure 4. Make sure that the DAC has output low noise, or, if no modulation is needed, an RC low pass filtered by be inserted between the DAC and the LIS pin. See Figure 5.

The LIO can still be used to monitor the output current when the LIS is adjusted. 0V to 2.5V indicates the laser current of from 0A to 2A linearly.

### Monitoring the Output Current

The output current of the driver can be monitored by measuring the voltage on the LIO pin. This feature is very useful for micro-controller based system where the ADC is available and monitoring the current in real time is required. This pin provides a very low noise voltage signal which is proportional to the output current:

$$V_{LIO} \text{ (V)} = 2.5 \times I_{OUT} / 2.0 \text{ (V)}.$$

For example, when the output signal equals to 2.5V, the output current is 2A.

LIO can be used to drive an ADC directly, and also be measured by a multimeter during debugging process.

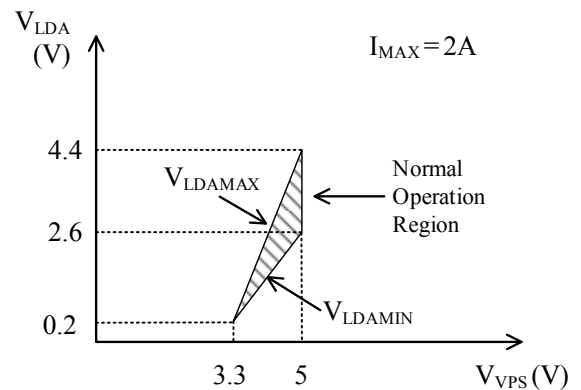


Figure 6.  $V_{VPS}$  &  $V_{LDA}$

### Driver Power Consumption

The power consumption of the driver can be calculated by:

$$P_{DRIVER} = I_{IN} \times V_{VPS} - I_{OUT} \times V_{LDA},$$

where  $I_{OUT}$  is the output current;

$I_{IN}$  is the power supply input current;

$V_{VPS}$  is the power supply voltage;

$V_{LDA}$  is the voltage across the laser diode;

$$\eta = I_{OUT} \times V_{LDA} / (I_{IN} \times V_{VPS}).$$

When the  $P_{DRIVER}$  exceeds 1W, a heat sink might be needed. Under this situation, if prefer not to use the heat sink, this is an option: lowering the driver power consumption by reducing the power supply voltage  $V_{VPS}$ . Please make sure:

$$V_{VPS} \geq V_{LDAMAX} + 0.15V_{VPS},$$

where  $V_{LDAMAX}$  is the maximum possible laser diode voltage.

**First Time Power Up**

Laser is a high value and vulnerable device. Faults in connections and damages done to the driver during soldering process may damage the laser permanently.

**To protect the laser, it is highly recommend to use 2 to 3 regular diodes of >2A to form a “dummy laser” and insert it in the place of the real laser diode, when powering up the driver for the first time. Use an oscilloscope to monitor the LDA voltage at times of**

**power-up and power-down, make sure that there is not over-shoot in voltage. At the same time, use an ammeter in serious with the dummy laser, to make sure that the output current is correct.**

After thorough checking free of faults, disconnect the dummy laser and connect the real laser in place.

The driver output voltage range for the laser is between 0.5 to 4V when powered by a 5V power supply.

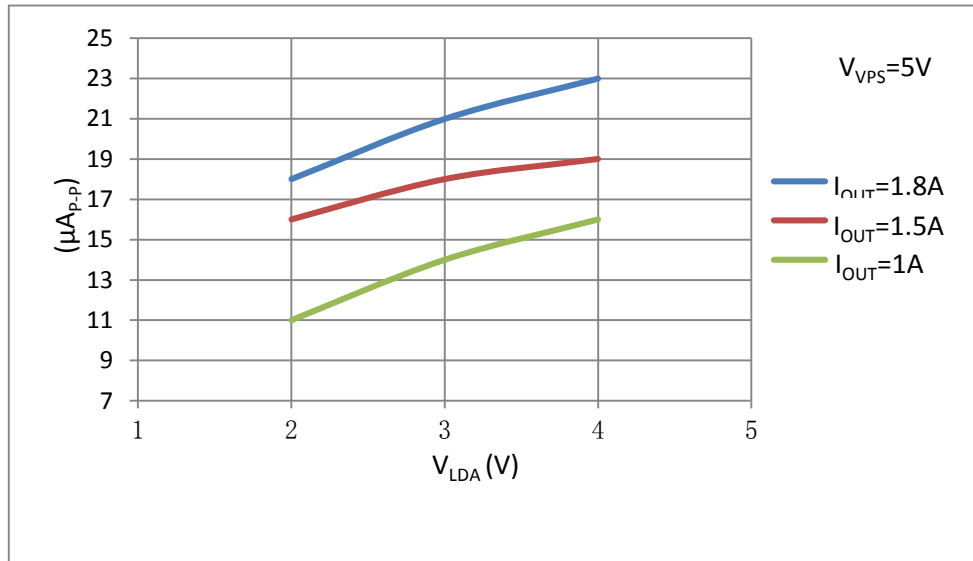


Figure 7. 1.  $V_{LDA}$  vs. Output Current Noise@0.1Hz~10Hz

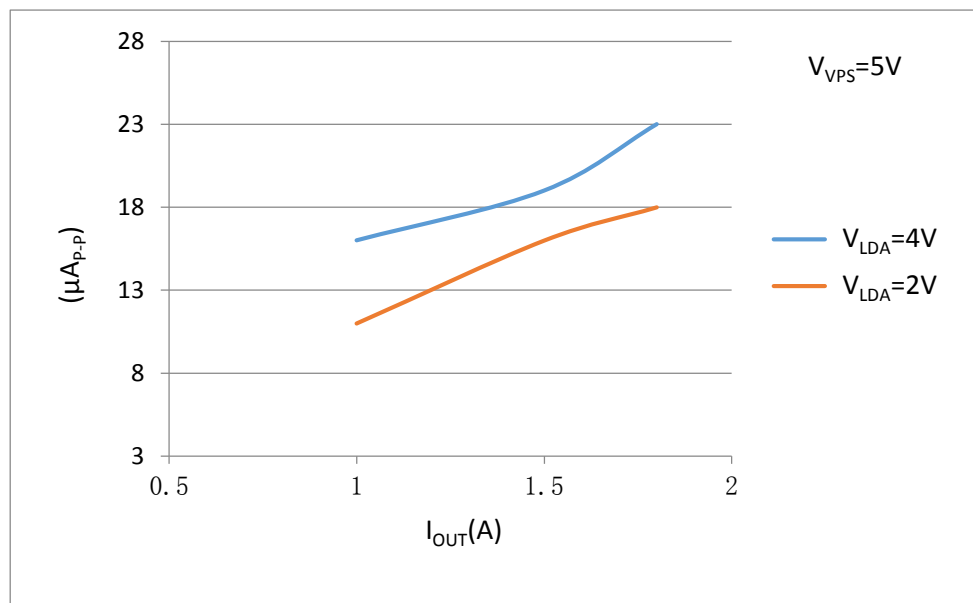


Figure 7. 2.  $I_{OUT}$  vs. Output Current Noise@0.1Hz~10Hz

**OUTLINE DIMENSIONS AND MOUNTING**

The driver comes in only one package: through hole mount. It is often called DIP (Dual Inline package) or D (short for DIP) package and has a part number: ATLS2A202D. Dimensions of the DIP package driver are shown in Figure 8

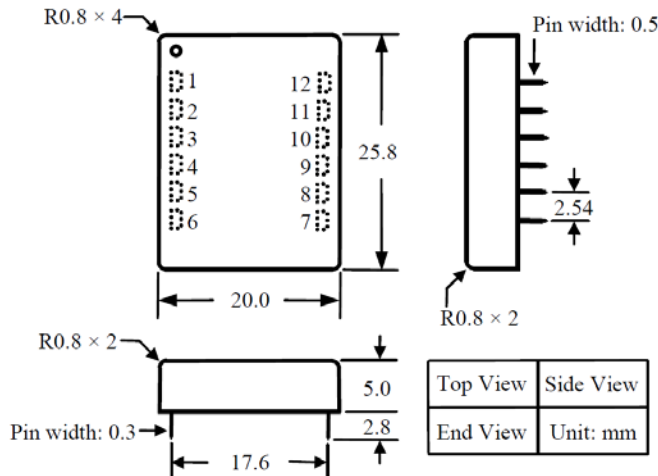


Figure 8. Dimensions of the DIP Package Driver

Figure 8 shows the foot-print which is seen from the end side of the PCB.

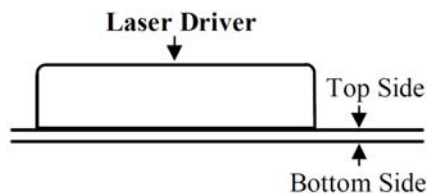


Figure 9. End View of the PCB Foot-print

Figure 9 shows the foot-print which is seen from the top side of the PCB, therefore, it is a “see through” view.

“Tent” (i.e. cover the entire via by the solder mask layer) all the vias under the driver, otherwise, the vias can be shorted by the bottom plate of the driver which is internally connected the ground.

See Figure 10 and 11, it is recommended to use large copper fills for VPS, LDC, and the LDA pins, and other pins if possible, to decrease the thermal resistance between the module and the supporting PCB, to lower the module temperature.

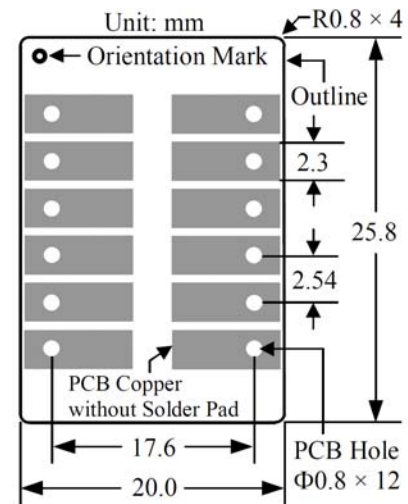


Figure 10. Top View of the Top Side PCB Foot-print

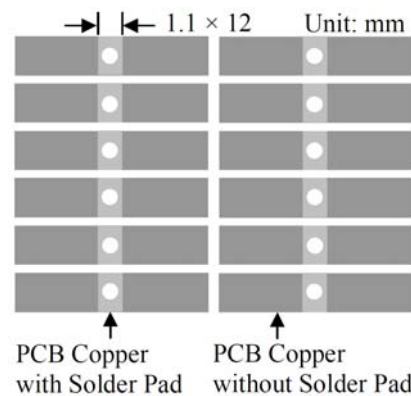


Figure 11. Top View of the Bottom Side PCB Foot-print

Figure 11 shows the foot-print which is seen from the bottom side of the PCB.

**Warning:** The through hole types of modules can only be soldered manually on the board by a solder iron of < 310°C (590°F), not go through a reflow oven process.





ORDERING INFORMATION

Table 3. Part Number

Part #	Description
ATLS2A202D	It can output up to 2A current and is packed in DIP package.

Table 4. Unit Price

Quantity	1 – 9	10 – 49	50 – 199	200 – 499	≥500
ATLS2A202D	\$79	\$76.6	\$72.2	\$67.8	\$63.4

NOTICE

- ATI warrants performance of its products for one year to the specifications applicable at the time of sale, except for those being damaged by excessive abuse. Products found not meeting the specifications within one year from the date of sale can be exchanged free of charge.
- ATI reserves the right to make changes to its products or to discontinue any product or service without notice, and advise customers to obtain the latest version of relevant information to verify, before placing orders, that information being relied on is current and complete.
- All products are sold subject to the terms and conditions of sale supplied at the time of order acknowledgment, including those pertaining to warranty, patent infringement, and limitation of liability. Testing and other quality control techniques are utilized to the extent ATI deems necessary to support this warranty. Specific testing of all parameters of each device is not necessarily performed, except those mandated by government requirements.
- Customers are responsible for their applications using ATI components. In order to minimize risks associated with the customers’ applications, adequate design and operating safeguards must be provided by the customers to minimize inherent or procedural hazards. ATI assumes no liability for applications assistance or customer product design.
- ATI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right of ATI covering or relating to any combination, machine, or process in which such products or services might be or are used. ATI’s publication of information regarding any third party’s products or services does not constitute ATI’s approval, warranty or endorsement thereof.
- IP (Intellectual Property) Ownership: ATI retains the ownership of full rights for special technologies and/or techniques embedded in its products, the designs for mechanics, optics, plus all modifications, improvements, and inventions made by ATI for its products and/or projects.