



High Temperature Difference TEC Modules

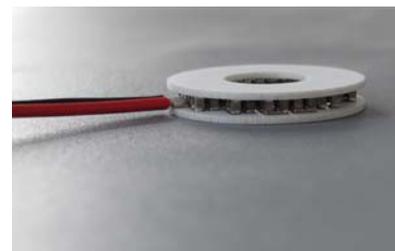
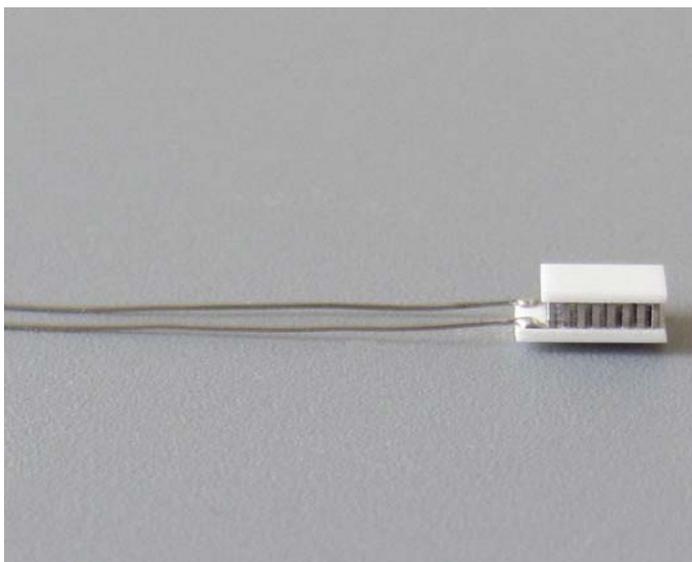
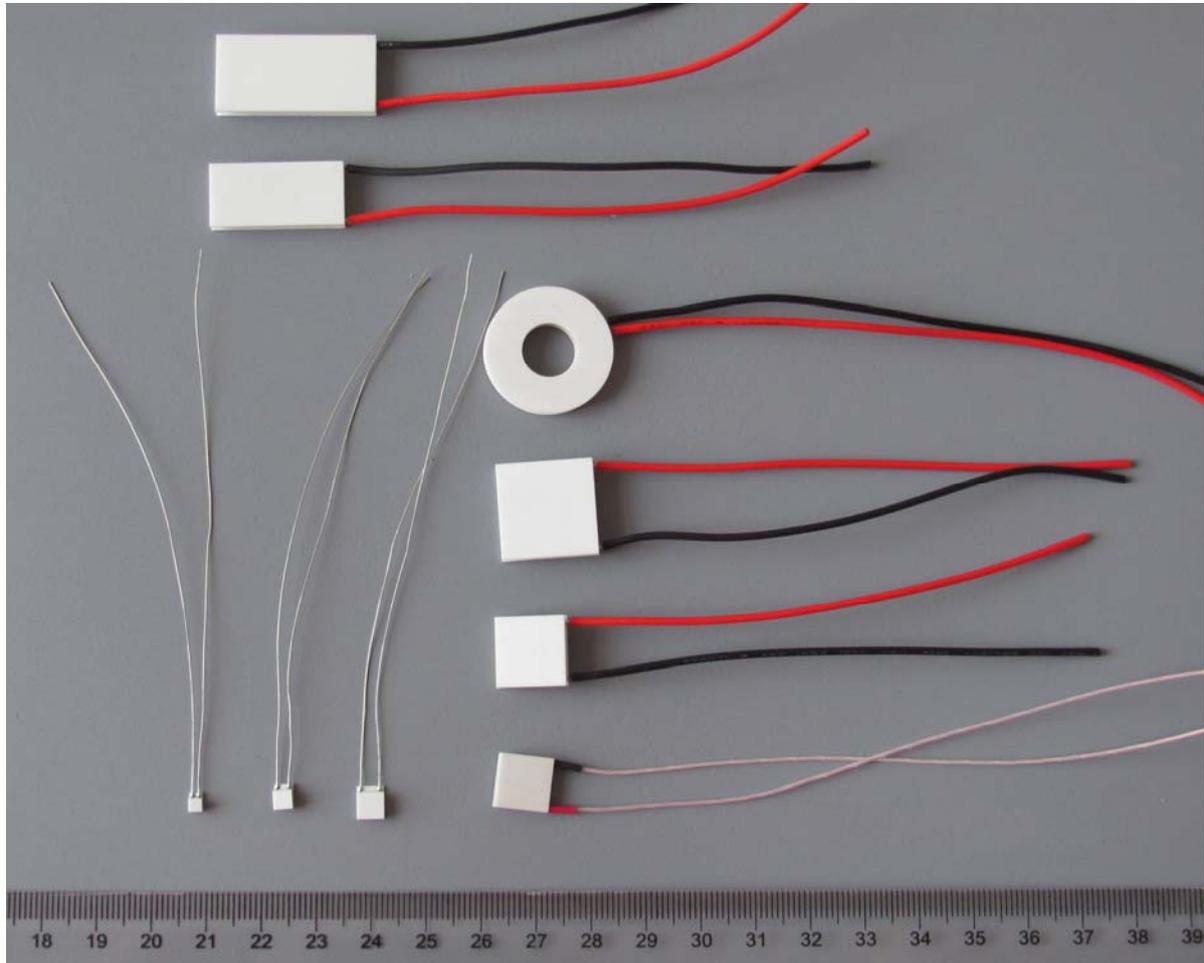


Figure 1. The Photo of Actual Sealed TEC modules



High Temperature Difference TEC

FEATURES

- Input Voltage: 1~9 V
- Maximum DT: up to 75°C
- Recommended operation current: 0.7 of I_{max}
- Recommended operation voltage: 0.8 of V_{max}
- Low Cost
- Long Life Time
- 100 % lead (Pb)-free and RoHS compliant

APPLICATIONS

Regulate the temperature of the target object with high changing speed and stabilize the temperature to a wide range with high precision. Widely used in solid state laser, icebox, air condition, IC's, optical components, CPU's, CCD cameras, etc.

DESCRIPTIONS

This series of TEC (Thermoelectric Cooler) modules has 8~71 pairs of Peltier elements inside. There are various options for maximum current, resulting in different power gratings, as shown in Table 1 below. They are designed for regulating the temperature of the target objects precisely and can be controlled by our TEC controllers to build highly stable and efficient temperature regulating systems. This series TECs can be used with our thermistors as well to achieve precise and stable temperature sensing.

How to Select a TEC Module

We've introduced serial numbering system for all types of TEC modules. Let's take ATE1-08-R4A as an example:

A	TE	(C)	1	08	R4	A
Analog Technologies	Thermal-electric elements	Circular shape with a center hole	Single stage TEC	Numbers of TE elements couples	0.4	Current: ampere

The TECs come with highly flat bare ceramic surfaces on the both sides, they can be mounted onto flat metal surfaces by inserting thin layers of thermally conductive filler materials, the so-called thermal pads, or placing a thin layer of thermal paste. When mounting, make sure that proper pressure is applied constantly to keep good thermal contacting between the metal and the TEC plates, minimizing thermal resistance between them.

The TECs can withstand strong orthogonal forces applied to the surface, but very vulnerable to tangent forces, especially shocking tangent forces. A small shocking tangent force can cause the Peltier elements crack inside. The crack may not cause operation problem initially, but it will grow with time, causing the TEC resistance to increase slowly, by the end, the TEC will stop operating.

This series of TECs are all non-sealed versions. The TECs, which have the edge area be sealed, can prevent moisture from getting into the Peltier elements and to extend the life time of the TECs. Non-sealed TECs feature that the efficiency is higher and can achieve higher maximum temperature difference between the two TEC plates.

For high end applications where good and reliable thermal contacts are needed between the TEC and the target object surfaces, the TEC ceramic surface can be metalized so that the TEC and the target object surfaces can be soldered together.

SPECIFICATIONS
Table 1.

Part #	I _{max} (A)	V _{max} (V)	Q _{max} (W)	DT _{max} (C)	Dimension (mm)				1-4 PCs	5-24 PCs	25-99 PCs	≥100 PCs	Note
					L _c	L _h	W	H					
ATE1-07-R8A	0.8	0.9	0.4	74	4		4	3	\$25.4	\$25.1	\$24.8	\$24.4	Non- sealed
ATE1-08-R4A	0.44	1	0.3	71.5	2.5	3.5	2.5	2.05	\$26.5	\$26.2	\$25.9	\$25.6	Non- sealed
ATE1-11-R8A	0.8	1.4	0.7	74.5	4		6	3	\$29.3	\$28.9	\$28.5	\$28.1	Non- sealed
ATE1-15-R6A	0.6	1.8	0.62	70	4.8		4.8	2.6	\$20.5	\$20.1	\$19.7	\$19.3	Non- sealed
ATE1-17-R8A	0.8	2.2	1	74.5	6		6	3	\$34.6	\$34.0	\$33.4	\$32.8	Non- sealed
ATE1-17-1.4A	1.4	2.2	2	72.5	6		6	2.47	\$34.6	\$34.0	\$33.4	\$32.8	Non- sealed
ATE1-17-1.9A	1.9	2.2	2.8	74.5	9		9	3.8	\$32.0	\$31.5	\$31.0	\$30.5	Non- sealed
ATE1-18-R4A	0.44	2.3	0.6	71.5	3.5	4.5	3.5	2.05	\$36.0	\$35.4	\$34.8	\$34.2	Non- sealed
ATE1-18-1R5A	1.53	2.3	2.2	71	6	7.6	6	2	\$37.7	\$37.1	\$36.5	\$35.9	Non- sealed
ATE1-31-R6A	0.6	3.8	1.5	75.5	8		8	3.5	\$38.6	\$38.0	\$37.4	\$36.8	Non- sealed
ATE1-31-1A	1	3.8	2.2	75	10		10	3.9	\$38.7	\$38.1	\$37.5	\$36.9	Non- sealed
ATE1-31-1.4A	1.4	3.8	3.7	72.5	8		8	2.7	\$38.8	\$38.2	\$37.6	\$37.0	Non- sealed
ATE1-31-1.6A	1.6	3.8	3.6	74	10		10	3	\$38.9	\$38.3	\$37.7	\$37.1	Non- sealed
ATE1-31-1.8A	1.8	3.9	4.8	75.5	15		15	4.8	\$36.8	\$36.2	\$35.6	\$35.0	Non- sealed
ATE1-31-1.9A	1.9	3.9	5.1	74.5	13		13	3.8	\$37.9	\$37.3	\$36.7	\$36.1	Non- sealed
ATE1-31-2.2A	2.2	3.9	5.5	72.5	10		10	2.5	\$39.7	\$39.1	\$38.5	\$37.9	Non- sealed
ATE1-31-3A	3	3.9	8.1	74.5	15		15	3.8	\$38.1	\$37.5	\$36.9	\$36.3	Non- sealed
ATE1-32-R4A	0.44	4.1	1.1	71.5	5	6	5	2.05	\$42.7	\$42.1	\$41.5	\$40.9	Non- sealed
ATE1-63-1.9A	1.9	8	10.4	74.5	25		12	3.8	\$42.4	\$41.8	\$41.2	\$40.6	Non- sealed
ATE1-63-3.4A	3.4	8	18.8	74.5	15		20	3.6	\$46.1	\$45.5	\$44.9	\$44.3	Non- sealed
ATE1-65-R8A	0.8	8.3	4.2	74.5	11		12	3	\$54.9	\$54.1	\$53.3	\$52.5	Non- sealed
ATE1-71-1.9A	1.9	9	11.7	74.5	18		18	3.8	\$42.8	\$42.2	\$41.6	\$41.0	Non- sealed

Part #	I _{max} (A)	V _{max} (V)	Q _{max} (W)	DT _{max} (C)	fo Outer Dia.	fin Inner Dia.	Height	1-4 PCs	5-24 PCs	25-99 PCs	≥100 PCs	Note
ATEC1-38-3.4A	3.4	4.8	11.3	74.5	24mm	10mm	3.6mm	\$30.6	\$30.1	\$29.6	\$29.1	Non- sealed
ATEC1-49-3AS	3	5.5	12.6	67	26mm	11mm	3.3mm	\$12.0	\$11.4	\$10.8	\$10.2	Sealed

* DT_{max}: DT stands for Differential Temperature between TEC's 2 plates



High Temperature Difference TEC

APPLICATION INFORMATION

As shown in Table 1, the DTmax, the maximum temperature difference between the 2 TEC plates, is between 71.5 C and 75.5 C. This is the normal value for a single stage TEC module. When needing a higher DTmax, 2 or 3 stage TECs must be utilized. Contact us for details.

TEC modules can be used for stabilizing laser chip temperature, to stabilize the wavelength and the working lasing mode, resulting in less or no mode hopping and stable output power.

Inversely, when applying a temperature difference between the TEC 2 plates, electricity can be generated. Thus, the TECs can be called TEGs (thermoelectric Generators).

When designing a thermal system by using TECs, one should choose the TEC module in the following way:

1. To achieve the maximum efficiency, it is essential to minimize the thermal resistance between the TEC plate surface and heat sink surface and between the TEC plate and the target object surface. The best way to minimize the thermal resistance is to mount the TEC modules' plates to the heat-sink and to the thermal load by soldering them together. This requires metalizing the TEC plate surfaces first. The 2nd best way is to apply a thin layer of thermal paste between the TEC plates and the heat-sink and the target object surfaces. Constant pressure is needed between the TEC plates and heat-sink and the target object surfaces. Thermal pad material, or so called thermal filler pads, can be used to replace the thermal paste. But this may increase the thermal resistance between the TEC plates and the heat-sink and the target object surfaces. Therefore, thermal paste is recommended to be applied between the TEC plates and the heat-sink. One of such products is Type 44 Heat Sink Compound 1/2 FL.OZ. made by Allied. More detail technical data about this material can be found here: <http://www.alliedelec.com/search/productdetail.aspx?SK>

[U=7964390](#). The 3rd best way is to use thermally conductive epoxy, to glue the TEC surface and the heat-sink and the target object surfaces together. This approach is the least reliable because the epoxy may lose its adhere power as time goes.

2. To achieve high COP, Coefficient of Performance, which is defined as:

$$COP = \text{thermal power} / \text{electric power},$$

the ratio between the TEC's output thermal power and the input electric power. Apparently, a high COP leads to low power system consumption, thus, high efficiency. The key to achieve high COP is to design the system with a low maximum temperature difference between the 2 TEC plates (the hot side and the cold side), DT. When the operating DT can be kept to be $\leq 30^{\circ}\text{C}$, the COP can be as high as 2, a very good result.

3. When the required maximum temperature difference is low, such as $< 30^{\circ}\text{C}$, a large TEC module can be used to drive small thermal load, resulting in a low DT, thus high COP and efficiency.
4. It is not hard to design in a TEC system, but does require some understanding of heat transfer and a good grasp of your applications.
5. ATE1-17-R8A, ATE1-18-R4A, ATE1-31-R6A, ATE1-31-1A, ATE1-31-1.4A, ATE1-31-1.6A, ATE1-31-1.8A, ATE1-31-1.9A, ATE1-31-2.2A, ATE1-32-R4A, ATE1-63-1.9A, ATE1-63-3.4A, and ATE1-71-1.9A can be driven by our quality TEC controller, TECA1-5V-5V-D, see datasheet: <http://www.analogtechnologies.com/document/TECA1-XV-XV-D.pdf>. ATE1-08-R4A, ATE1-17-1.4A, ATE1-17-1.9A and ATE1-31-3A can be driven by TEC-5V4A-D, see datasheet: <http://www.analogtechnologies.com/document/TEC5V4A-D.pdf>.

MECHANICAL DIMENSIONS

The mechanical dimensions of the TECs are shown below.

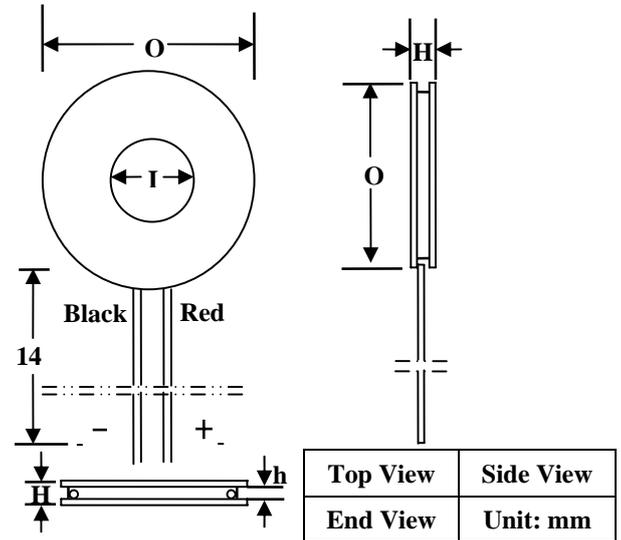
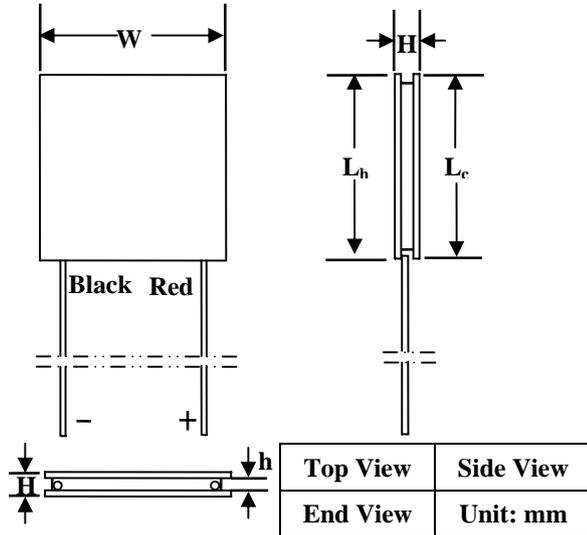


Figure 2. Mechanical dimensions of TECs in square shape

Figure 3. Mechanical dimensions of ATEC1-38-3.4A

The TECs come in square or circular shape, small size, and light weight. The L_c , L_h , W dimensions are the same in one TEC, only the H dimension varies with different currents, thus different powers, as shown in Table 1.



CAUTIONS

1. Never apply electricity to TEC modules without having heat sinks attached properly.
2. Always keep the current less than I_{max} , to avoid thermal run-away disaster.

NOTICE

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